# Alexander Belton<sup>1†</sup>, Dominique Guillot<sup>2‡</sup>, Apoorva Khare<sup>3§</sup>, and Mihai Putinar<sup>4,5¶</sup>

<sup>1</sup>Lancaster University, Lancaster, UK

<sup>2</sup>University of Delaware, Newark, DE, USA

<sup>3</sup>Stanford University, Stanford, CA, USA

<sup>4</sup>University of California at Santa Barbara, CA, USA

<sup>5</sup>Newcastle University, Newcastle upon Tyne, UK

**Abstract.** A classical result by Schoenberg (1942) identifies all real-valued functions that preserve positive semidefiniteness (psd) when applied entrywise to matrices of arbitrary dimension. Schoenberg's work has continued to attract significant interest, including renewed recent attention due to applications in high-dimensional statistics. However, despite a great deal of effort in the area, an effective characterization of entrywise functions preserving positivity in a fixed dimension remains elusive to date. As a first step, we characterize new classes of polynomials preserving positivity in fixed dimension. The proof of our main result is representation theoretic, and employs Schur polynomials. An alternate, variational approach also leads to several interesting consequences including (a) a hitherto unexplored Schubert cell-type stratification of the cone of psd matrices, (b) new connections between generalized Rayleigh quotients of Hadamard powers and Schur polynomials, and (c) a description of the joint kernels of Hadamard powers.

**Résumé.** Un résultat classique de Schoenberg (1942) fournit une caractérisation des fonctions réelles préservant la positivité lorsque appliquées aux entrées des matrices semidéfinie positives de dimension arbitraire. Le travail de Schoenberg est toujours d'actualité, et a récemment reçu beaucoup d'attention suite à ses applications aux statistiques de haute dimension. Néanmoins, l'obtention d'une caractérisation utile des fonctions préservant la positivité lorsque la dimension est fixe demeure un problème ouvert. Afin d'attaquer ce problème, nous caractérisons de nouvelles classes de polynômes qui préservent la positivité en dimension finie. La preuve de notre résultat principal implique plusieurs idées provenant de la théorie de la représentation, et utilise les polynômes de Schur. Nous explorons aussi une approche variationnelle parallèle qui mène à de nombreux résultats intéressants: (a) une stratification du cône des matrices semidéfinies positives, (b) de nouvelles connexions entre les quotients de Rayleigh généralisés des puissances d'Hadamard et les polynômes de Schur, et (c) une description du noyau simultané des puissances d'Hadamard.

Keywords. positive definite matrix, Hadamard product, Schur polynomial, entrywise function, Rayleigh quotient

1365-8050 © 2016 Discrete Mathematics and Theoretical Computer Science (DMTCS), Nancy, France

<sup>&</sup>lt;sup>†</sup>Email: a.belton@lancaster.ac.uk

<sup>&</sup>lt;sup>‡</sup>Email: dguillot@udel.edu

<sup>§</sup>Email: khare@stanford.edu

<sup>¶</sup>Email: mputinar@math.ucsb.edu, mihai.putinar@ncl.ac.uk

## 1 Introduction and main result

Endomorphisms of matrix spaces with positivity constraints have long been studied in connection with a variety of topics: the geometry of classical domains in complex space, matrix monotone functions [18], positive definite functions [3, 4, 7, 23, 26], hyperbolic or positive definite polynomials and global optimization algorithms [6, 14]. In this paper, we study the entrywise calculus on the cone of positive semidefinite matrices, with the aim of characterizing positivity preservers in that setting.

Given  $\rho \in (0, \infty)$ , let  $D(0, \rho)$  and  $\overline{D}(0, \rho)$  denote the open and closed complex discs of radius  $\rho$  centered at the origin, respectively. Given integers  $1 \le k \le N$  and a set  $I \subset \mathbb{C}$ , let  $\mathcal{P}_N^k(I)$  denote the set of positive semidefinite  $N \times N$  matrices, with entries in I and rank at most k. Let  $\mathcal{P}_N(I) := \mathcal{P}_N^N(I)$ . A function  $f : I \to \mathbb{C}$  induces an entrywise map of matrix spaces, sending  $A = (a_{jk}) \in \mathcal{P}_N(I)$  to  $f[A] := (f(a_{jk}))$ . Starting from positive definite functions [7, 23, 26], it is natural to classify all entrywise functions f[-] preserving positive semidefiniteness (positivity). It is an easy consequence of the Schur product theorem [24] that if  $f : (-\rho, \rho) \to \mathbb{R}$  is analytic with non-negative Taylor coefficients, then  $f[A] \in \mathcal{P}_N$  for all  $A \in \mathcal{P}_N$  and all  $N \ge 1$ . A celebrated result of Schoenberg shows the converse.

**Theorem 1.1 (Schoenberg, [23])** Given a continuous function  $f : [-1,1] \to \mathbb{R}$ , the entrywise map  $f[-] : \mathcal{P}_N([-1,1]) \to \mathcal{P}_N(\mathbb{R})$  for all  $N \ge 1$  if and only if f is analytic on [-1,1] and absolutely monotonic on [0,1], i.e., f has a Taylor series with non-negative coefficients convergent on  $\overline{D}(0,1)$ .

Schoenberg's theorem and its ramifications were persistently examined and revisited, see for instance Rudin [22], Berg–Christensen–Ressel–Porcu [3, 4, 8], Hiai [16], to cite only a few. The present investigation evolves out of Schoenberg's result by imposing the challenging condition of dealing with matrices of *fixed* dimension. This is a much harder question, that is open despite tremendous activity in the field.

It is worth recalling that Schoenberg was motivated by the problem of isometrically embedding positive definite metrics into Hilbert space; see e.g. [26]. In [23], he sought to classify positive definite functions on spheres  $S^{d-1} \subset \mathbb{R}^d$ . This can be reformulated via Gram matrices, as classifying the entrywise functions preserving positivity on correlation matrices of all dimensions, with rank at most d. A strong need to study the fixed dimension case also arises out of current demands from the fast expanding field of data science. In modern settings, functions f are often applied entrywise to high-dimensional correlation matrices A, in order to improve their properties (better conditioning, Markov random field structure, etc.); see e.g. [5, 15, 21]. The "regularized" matrices f[A] are ingredients in further statistical procedures, for which it is critical that they be positive semidefinite. Also, in applications the dimension of the problem is known, and so, preserving positivity in all dimensions unnecessarily limits the class of functions that can be used. There is thus strong motivation from applications to study the fixed dimension case.

While characterization results have recently been obtained in fixed dimension under additional rank and sparsity constraints arising in practice [11, 12, 13], the original problem in fixed dimension has remained open for more than 70 years. A necessary condition for continuous functions was developed by Horn (and attributed to Loewner) in his doctoral thesis [17]. The result was recently extended in [11] to low-rank matrices, and without the continuity assumption:

**Theorem 1.2 (Horn [17], Guillot–Khare–Rajaratnam [11])** Suppose  $f : I \to \mathbb{R}$ , where  $I := (0, \rho)$ and  $0 < \rho \leq \infty$ . Fix an integer  $N \geq 2$  and suppose that  $f[A] \in \mathcal{P}_N(\mathbb{R})$  for any  $A \in \mathcal{P}_N^2(I)$  of the form  $A = a\mathbf{1}_{N\times N} + \mathbf{uu}^T$ , where  $a \in (0, \rho)$ ,  $\mathbf{u} \in [0, \sqrt{\rho - a})^N$ , and  $\mathbf{1}_{N\times N} \in \mathcal{P}_N^1(\mathbb{R})$  has entries all one. Then  $f \in C^{N-3}(I)$ , with  $f^{(k)}(x) \geq 0$  for all  $x \in I$ ,  $0 \leq k \leq N - 3$ , and  $f^{(N-3)}$  is a convex non-decreasing function on I. If, further,  $f \in C^{N-1}(I)$ , then  $f^{(k)}(x) \geq 0$  for all  $x \in I$  and  $0 \leq k \leq N - 1$ .

Note that all real power functions  $x^{\alpha}$  preserve positivity on  $\mathcal{P}_{N}^{1}((0,\rho))$ , yet such functions need not have even a single positive derivative on  $(0,\rho)$ . However, Theorem 1.2 shows that working with a small one-parameter extension of  $\mathcal{P}_{N}^{1}((0,\rho))$  guarantees that  $f^{(k)}$  is non-negative on  $(0,\rho)$  for  $0 \le k \le N-3$ .

Theorem 1.2 is sharp, since the entrywise power  $x^{\alpha}$ , for  $\alpha \in (N - 2, N - 1)$ , preserves positivity on  $\mathcal{P}_N((0, \rho))$ , but not on  $\mathcal{P}_{N+1}((0, \rho))$ . See [9, 10, 16] for more on entrywise powers preserving positivity. Consequently, in this paper we study analytic functions which preserve  $\mathcal{P}_N$  for fixed N, when applied entrywise. Note that any analytic function mapping  $(0, \rho)$  to  $\mathbb{R}$  necessarily has real Taylor coefficients. Now a variant of Theorem 1.2 for analytic functions, obtained using generalized Vandermonde matrices, shows that the same conclusions hold if one works merely with rank-one matrices:

**Lemma 1.3** Let  $0 < \rho \le \infty$  and  $f(z) = \sum_{k \ge 0} c_k z^k : D(0, \rho) \to \mathbb{R}$  be analytic. If  $f[-] : \mathcal{P}^1_N((0, \rho)) \to \mathcal{P}_N(\mathbb{R})$  for some integer  $N \ge 1$ , then the first N non-zero Taylor coefficients  $c_j$  are strictly positive.

Given  $f(z) = \sum_{k\geq 0} c_k z^k$  such that  $c_0, \ldots, c_{N-1} > 0$ , a natural challenging question to ask is if the next non-zero coefficient  $c_M$  can be negative; and if so, to provide a negative threshold for the coefficient  $c_M$ , where  $M \geq N$ . Resolving these questions, open since Horn's 1969 paper, provides a quantitative version of Schoenberg's theorem. Our main result answers these questions in the affirmative, and illustrates the complexity of the negative threshold bound. It is also surprising that preserving positivity on  $\mathcal{P}_N(\overline{D}(0,\rho))$  is equivalent to preserving positivity on the much smaller set of real rank-one matrices,  $\mathcal{P}_N^1((0,\rho))$ .

**Theorem 1.4** Fix  $\rho > 0$  and integers  $N \ge 1$ ,  $M \ge 0$  and let  $f(z) := \sum_{j=0}^{N-1} c_j z^j + c' z^M$  be a polynomial with real coefficients. Then the following are equivalent.

- 1. f[-] preserves positivity on  $\mathcal{P}_N(\overline{D}(0,\rho))$ .
- 2. Either  $c_0, \ldots, c_{N-1}, c' \ge 0$ , or  $c_0, \ldots, c_{N-1} > 0$  and  $c' \ge -\mathcal{C}(\mathbf{c}; z^M; N, \rho)^{-1}$ , where

$$\mathbf{c} := (c_0, \dots, c_{N-1}), \qquad \mathcal{C}(\mathbf{c}; z^M; N, \rho) := \sum_{j=0}^{N-1} {\binom{M}{j}}^2 {\binom{M-j-1}{N-j-1}}^2 \frac{\rho^{M-j}}{c_j}.$$
(1.5)

3. f[-] preserves positivity on  $\mathcal{P}^1_N((0,\rho))$ .

Notice that the condition  $c_0, \ldots, c_{N-1} \ge 0$  follows from Lemma 1.3. Theorem 1.4 now provides the first construction of a polynomial that preserves positivity on  $\mathcal{P}_N$ , but not on  $\mathcal{P}_{N+1}$ . Indeed, this is the case when  $-\mathcal{C}(\mathbf{c}; z^M; N, \rho)^{-1} \le c_N < 0$ , by Theorem 1.2.

**Remark 1.6** Theorem 1.4 can naturally be used to provide a sufficient condition for an arbitrary analytic function to preserve positivity on  $\mathcal{P}_N(\overline{D}(0,\rho))$ . The reader is referred to [1] for more details.

### 2 Proof of the main result

We now sketch the proof of Theorem 1.4. Recall that the Schur product theorem provides the first examples of entrywise functions preserving positivity, namely, the functions of the form  $\sum_{k=0}^{\infty} c_k z^k$  with  $c_k \ge 0$ . That these are the only functions preserving positivity in all dimensions is Schoenberg's theorem (Theorem 1.1). In some sense, our proof of the fixed dimension case in Theorem 1.4 returns to Schur by

crucially using symmetric functions among other techniques, specifically, Schur polynomials and Schur complements. Indeed, the technical heart of the proof is an explicit Jacobi–Trudi type identity, which is valid in any field and may be interesting in its own right.

Given a partition, i.e., a non-increasing N-tuple of non-negative integers  $\mathbf{n} = (n_N \ge \cdots \ge n_1)$ , define the corresponding Schur polynomial  $s_{\mathbf{n}}(x_1, \dots, x_N)$  over a field  $\mathbb{F}$  with at least N elements, to be the unique polynomial extension to  $\mathbb{F}^N$  of  $s_{\mathbf{n}}(x_1, \dots, x_N) := \frac{\det(x_i^{n_j+N-j})}{\det(x_i^{N-j})}$  for pairwise distinct  $x_i \in$  $\mathbb{F}$ . Note that the denominator equals the Vandermonde determinant  $\Delta_N(x_1, \dots, x_N) := \det(x_i^{N-j}) = \prod_{1 \le i < j \le N} (x_i - x_j)$ ; thus,

$$s_{\mathbf{n}}(1,\ldots,z^{N-1}) = \prod_{1 \le i < j \le N} \frac{z^{n_j+j} - z^{n_i+i}}{z^j - z^i}, \qquad s_{\mathbf{n}}(1,\ldots,1) = \prod_{1 \le i < j \le N} \frac{n_j - n_i + j - i}{j - i}.$$
 (2.1)

The last equation can also be deduced from the Weyl Character Formula in type A; see, for example, [19, Chapter I.3, Example 1] for more details about Schur polynomials and the theory of symmetric functions.

To prove Theorem 1.4, we study the determinants of a linear pencil

$$p(t) = p_t[A] := \det \left( t(c_0 \mathbf{1}_{N \times N} + c_1 A + \dots + c_{N-1} A^{\circ (N-1)}) - A^{\circ M} \right)$$

for a general rank-one matrix  $A = \mathbf{u}\mathbf{v}^T$ , where  $\mathbf{u} = (u_1, \dots, u_N)^T$  and  $\mathbf{v} := (v_1, \dots, v_N)^T \in \mathbb{F}^N$  for  $N \ge 1$ . The technical heart of the proof involves the following explicit determinantal identity.

**Theorem 2.2** Let  $M \ge N \ge 1$  be integers, and  $c_0, \ldots, c_{N-1} \in \mathbb{F}^{\times}$  be non-zero scalars in any field  $\mathbb{F}$ . Define the polynomial  $p_t(z) := t(c_0 + \cdots + c_{N-1}z^{N-1}) - z^M$ . Now define the hook partition

$$\mu(M, N, j) := (M - N + 1, 1, \dots, 1, 0, \dots, 0)$$
(2.3)

(N - j - 1 ones, j zeros) for  $0 \le j < N$ . Then the following identity holds for all  $\mathbf{u}, \mathbf{v} \in \mathbb{F}^N$ :

$$\det p_t[\mathbf{u}\mathbf{v}^T] = t^{N-1}\Delta_N(\mathbf{u})\Delta_N(\mathbf{v})\prod_{j=0}^{N-1} c_j \Big(t - \sum_{j=0}^{N-1} \frac{s_{\mu(M,N,j)}(\mathbf{u})s_{\mu(M,N,j)}(\mathbf{v})}{c_j}\Big).$$
(2.4)

Moreover,  $s_{\mu(M,N,j)}(1,\ldots,1) = \binom{M}{j} \binom{M-j-1}{N-j-1}$  for all  $0 \le j < N$ .

**Sketch of proof.** We first show the following fact: Let  $A := \mathbf{uv}^T$  for  $\mathbf{u}, \mathbf{v} \in \mathbb{F}^N$ . Given a strict partition  $\mathbf{n} = (n_m > n_{m-1} > \cdots > n_1)$  and scalars  $(c_{n_1}, \ldots, c_{n_m}) \in \mathbb{F}^m$ , the following determinantal identity holds:

$$\det \sum_{j=1}^{m} c_{n_j} A^{\circ n_j} = \Delta_N(\mathbf{u}) \Delta_N(\mathbf{v}) \sum_{\mathbf{n}' \subset \mathbf{n}, \ |\mathbf{n}'| = N} s_{\lambda(\mathbf{n}')}(\mathbf{u}) s_{\lambda(\mathbf{n}')}(\mathbf{v}) \prod_{k=1}^{N} c_{n'_k}.$$
 (2.5)

Here,  $\lambda(\mathbf{n}') := (n'_N - N + 1 \ge n'_{N-1} - N + 2 \ge \cdots \ge n'_1)$  is obtained by subtracting the staircase partition  $(N-1,\ldots,0)$  from  $\mathbf{n}' := (n'_N > \cdots > n'_1)$ , and the sum is over all subsets  $\mathbf{n}'$  of cardinality N.

The proof of (2.5) uses the matrix  $X(\mathbf{u},\mathbf{n}) := (u_j^{n_k})_{1 \le j \le N, 1 \le k \le m}$  and the Cauchy–Binet formula applied to  $\sum_{j=1}^{m} c_{n_j} A^{\circ n_j} = X(\mathbf{u}, \mathbf{n}) \cdot \operatorname{diag}(c_{n_1}, \dots, c_{n_m}) \cdot X(\mathbf{v}, \mathbf{n})^T.$ 

Using (2.5), we now prove (2.4). Recall the Laplace formula: if B and C are  $N \times N$  matrices, then  $det(B+C) = \sum_{\mathbf{n} \in \{1,\dots,N\}} det M_{\mathbf{n}}(B;C), \text{ where } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix formed by replacing the rows of } M_{\mathbf{n}}(B;C) \text{ is the matrix for$ 

B labelled by elements of n with the corresponding rows of C. In particular, if  $B = \sum_{j=0}^{N-1} c_j A^{\circ j}$  then

$$\det p_t[A] = \det(tB - A^{\circ M}) = t^N \det B - t^{N-1} \sum_{j=1}^N \det M_{\{j\}}(B; A^{\circ M}),$$
(2.6)

since the determinant in each of the remaining terms contains at least two rows of the rank-one matrix  $A^{\circ M}$ . Applying (2.5) yields: det  $B = \Delta_N(\mathbf{u})\Delta_N(\mathbf{v})c_0\cdots c_{N-1}$ . Moreover, the coefficient of  $t^{N-1}$  is precisely det  $p_1[A] - \det B$ , and det  $p_1[A]$  can be computed using (2.5) again, to yield:

$$\det p_1[A] = \det B - \Delta_N(\mathbf{u})\Delta_N(\mathbf{v})c_0\cdots c_{N-1}\sum_{j=0}^{N-1} \frac{s_{\mu(M,N,j)}(\mathbf{u})s_{\mu(M,N,j)}(\mathbf{v})}{c_j}$$

since  $\mu(M, N, j) = \lambda((M, N - 1, N - 2, ..., j + 1, \hat{j}, j - 1, ..., 0))$  for  $0 \le j < N$ . This proves the identity (2.4). The final assertion follows from (2.1), or by using the dual Jacobi-Trudi (Von Nägelsbach-Kostka) identity [19, Chapter I, Eqn. (3.5)], or Stanley's hook-content formula [25, Theorem 15.3].

Equipped with Theorem 2.2, we now outline how to show the main result.

Sketch of proof of Theorem 1.4. Clearly  $(1) \implies (3)$ . Now if  $0 \le M < N$ , then  $C(\mathbf{c}; z^M; N, \rho) = c_M^{-1}$ . Thus, in this case,  $(2) \implies (1)$  by the Schur product theorem, and moreover,  $(3) \implies (2)$  by Lemma 1.3.

Suppose for the remainder of the proof that  $M \geq N$ ; we also set  $c_M := c'$ . We first show that (3)  $\implies$  (2). It suffices to consider the case  $c_M < 0 < c_0, \ldots, c_{N-1}$ . Define  $p_t(z)$  as in Theorem 2.2, and set  $t := |c_M|^{-1}$ . By Equation (2.4),

$$0 \le \det p_t[\mathbf{u}\mathbf{u}^T] = t^{N-1}\Delta_N(\mathbf{u})^2 c_0 \cdots c_{N-1} \left( t - \sum_{j=0}^{N-1} \frac{s_{\mu(M,N,j)}(\mathbf{u})^2}{c_j} \right).$$
(2.7)

Set  $u_k := \sqrt{\rho}(1 - t'\epsilon_k)$ , with pairwise distinct  $\epsilon_k \in (0, 1)$ , and  $t' \in (0, 1)$ . Thus,  $\Delta_N(\mathbf{u}) \neq 0$ . Taking the limit as  $t' \to 0^+$ , since the final term in (2.7) must be non-negative, it follows by Theorem 2.2 that

$$t = |c_M|^{-1} \ge \sum_{j=0}^{N-1} \frac{s_{\mu(M,N,j)}(\sqrt{\rho},\dots,\sqrt{\rho})^2}{c_j} = \sum_{j=0}^{N-1} s_{\mu(M,N,j)}(1,\dots,1)^2 \frac{\rho^{M-j}}{c_j} = \mathcal{C}(\mathbf{c};z^M;N,\rho).$$

It remains to show that (2)  $\implies$  (1) when  $M \ge N$  and  $c_M < 0 < c_0, \ldots, c_{N-1}$ . The major step involves showing that f[-] preserves positivity on  $\mathcal{P}^1_N(\overline{D}(0,\rho))$ . Given  $1 \le m \le N$ , define

$$C_m := \sum_{j=0}^{m-1} s_{\mu(M-N+m,m,j)}(1,\dots,1)^2 \frac{\rho^{m+M-N-j}}{c_{N-m+j}} = \mathcal{C}(\mathbf{c}_m; z^{M-N+m}; m, \rho),$$
(2.8)

where  $\mathbf{c}_m := (c_{N-m}, \ldots, c_{N-1})$ . One now shows that

$$0 < C_1 = \rho^{M-N+1}/c_{N-1} < C_2 < \dots < C_N = \mathcal{C}(\mathbf{c}; z^M; N, \rho)$$

Next, we claim that for all  $1 \leq m \leq N$  and  $A = \mathbf{uu}^* \in \mathcal{P}^1_N(\overline{D}(0,\rho))$ , every principal  $m \times m$ submatrix of the matrix

$$L := C_m (c_{N-m} \mathbf{1}_{N \times N} + c_{N-m+1} A + \dots + c_{N-1} A^{\circ(m-1)}) - A^{\circ(m+M-N)}$$
(2.9)

is positive semidefinite. Notice that the rank-one case of (1) follows by setting m = N.

The claim is shown by induction on m, with the m = 1 case immediate. Suppose the result holds for  $m-1 \ge 1$ . Henceforth, given a non-empty set  $\mathbf{n} \subset \{1, \ldots, N\}$  and an  $N \times N$  matrix B, denote by  $B_{\mathbf{n}}$ the principal submatrix of B consisting of those rows and columns labelled by elements of J; similarly define the subvector  $\mathbf{u}_{\mathbf{n}}$  of a vector  $\mathbf{u}$ . If  $\mathbf{n} \subset \{1, \dots, N\}$  has cardinality m then,

$$\det L_{\mathbf{n}} = C_m^{m-1} |\Delta_m(\mathbf{u}_n)|^2 \prod_{j=1}^m c_{N-j} \left( C_m - \sum_{j=0}^{m-1} \frac{|s_{\mu(M-N+m,m,j)}(\mathbf{u}_n)|^2}{c_{N-m+j}} \right)$$

by Theorem 2.2 with  $\mathbf{v} = \overline{\mathbf{u}_n}$ . By the triangle inequality in  $\mathbb{C}$  and the fact that the coefficients of Schur polynomials are non-negative, one shows that det  $L_{\mathbf{n}} \geq 0$  if  $|\mathbf{n}| = m$ . If on the other hand  $|\mathbf{n}| = k < m$ ,

$$L_{\mathbf{n}} \geq C_m(c_{N-k}A_{\mathbf{n}}^{\circ(m-k)} + \dots + c_{N-1}A_{\mathbf{n}}^{\circ(m-1)}) - A_{\mathbf{n}}^{\circ(m+M-N)}$$
  
$$\geq A_{\mathbf{n}}^{\circ(m-k)} \circ \left( C_k(c_{N-k}\mathbf{1}_{k\times k} + \dots + c_{N-1}A_{\mathbf{n}}^{\circ(k-1)}) - A_{\mathbf{n}}^{\circ(k+M-N)} \right),$$

since  $C_m > C_k$ . Hence by the induction hypothesis, all principal  $m \times m$  submatrices of L are positive semidefinite. This shows the claim by induction on m, whence f[-] preserves positivity on  $\mathcal{P}_{N}^{1}(\overline{D}(0,\rho))$ .

Finally, to show the result for matrices in  $\mathcal{P}_N$  of all ranks, we induct on  $N \ge 1$ . Suppose (1) holds for  $N-1 \ge 1$ , and define  $p_t[B; M, \mathbf{d}] := t(d_0 \mathbf{1} + d_1 B + \dots + d_{n-1} B^{\circ(n-1)}) - B^{\circ(n+M)}$  for any square matrix B, where t is a real scalar and n is the length of the tuple  $\mathbf{d} = (d_0, \dots, d_{n-1})$ . It suffices to show the claim that  $p_t[A; M - N, \mathbf{c}] \ge 0$  for all  $t \ge \mathcal{C}(\mathbf{c}; z^M; N, \rho)$  and all  $A = (a_{ij}) \in \mathcal{P}_N(\overline{D}(0, \rho))$ . To show the claim, define  $\mathbf{u} := (a_{iN}/\sqrt{a_{NN}})^T \in \mathbb{C}^N$ , and use [9, Lemma 2.1] to show that

$$p_t[A; M-N, \mathbf{c}] = p_t[\mathbf{u}\mathbf{u}^*; M-N, \mathbf{c}] + \int_0^1 (A - \mathbf{u}\mathbf{u}^*) \circ Mp_{t/M}[\lambda A + (1-\lambda)\mathbf{u}\mathbf{u}^*; M-N, \mathbf{c}'] d\lambda,$$
(2.10)

where the (N-1)-tuple  $\mathbf{c}' := (c_1, 2c_2, \dots, (N-1)c_{N-1})$ . Notice that  $A - \mathbf{u}\mathbf{u}^*$  is the padding by a zero row and column, of the Schur complement of  $a_{NN}$  in A. Therefore the integrand in (2.10) is positive semidefinite if the matrix  $p_{t/M}[A_{\lambda}; M - N, \mathbf{c}']$  is, where  $A_{\lambda} \in \mathcal{P}_{N-1}(\overline{D}(0, \rho))$  is obtained by deleting the final row and column of  $\lambda A + (1 - \lambda)\mathbf{uu}^*$ . Finally, that  $p_{t/M}[A_{\lambda}; M - N, \mathbf{c}']$  is positive semidefinite follows by computing that  $\mathcal{C}(\mathbf{c}; z^M; N, \rho) \geq M\mathcal{C}(\mathbf{c}'; z^{M-1}; N-1, \rho)$ .

#### 3 Consequences of the main theorem

Theorem 1.4 leads to a host of consequences that initiate the development of an entrywise matrix calculus, in parallel to the well-studied functional calculus. We now discuss two of these consequences in detail: linear matrix inequalities and connections to Rayleigh quotients.

#### 3.1 Linear matrix inequalities for Hadamard powers

Theorem 1.4 can be equivalently reformulated as a linear matrix inequality that controls the spectrum of linear combinations of Hadamard powers of A.

**Theorem 3.1** Fix  $\rho > 0$ , integers  $M \ge N \ge 1$ , and scalars  $c_0, \ldots, c_{N-1} > 0$ . Then

$$A^{\circ M} \leq \mathcal{C}(\mathbf{c}; z^{M}; N, \rho) \cdot \left( c_0 \mathbf{1}_{N \times N} + c_1 A + \dots + c_{N-1} A^{\circ (N-1)} \right), \qquad \forall A \in \mathcal{P}_N(\overline{D}(0, \rho)), \quad (3.2)$$

where  $\leq$  stands for the Loewner ordering. Moreover, the constant  $C(\mathbf{c}; z^M; N, \rho)$  is sharp in (3.2).

Notice here that the right-hand side of (3.2) cannot involve fewer Hadamard powers, by Lemma 1.3.

A refined analysis of the proof of Theorem 1.4 shows that the matrix f[A] is generically positive definite, in a strong sense:

**Theorem 3.3** Fix  $\rho > 0$ , integers  $M \ge N \ge 1$ , and scalars  $c_0, \ldots, c_{N-1} > 0$ .

- 1. Suppose N > 1, and  $A \in \mathcal{P}_N(\overline{D}(0,\rho))$  has a row or column with pairwise distinct entries. Define  $f(z) := c_0 + \cdots + c_{N-1} z^{N-1} \mathcal{C}(\mathbf{c}; z^M; N, \rho)^{-1} z^M$ . Then f[A] is positive definite.
- 2. In particular, equality in (3.2) is never attained on  $\mathcal{P}_N(\overline{D}(0,\rho))$  unless  $(N, A) = (1, \rho)$ .

As with the main theorem, the proof of (1) and (2) crucially uses symmetric functions, specifically, connections between Schur polynomials and Young tableaux.

Sketch of proof. It is also easy to show (2) for N = 1. Thus, assume N > 1. We first show that (2) follows from (1). Indeed, if (1) holds, then using  $\mathbf{u} \in [0, \sqrt{\rho}]^N$  with distinct entries, it follows that  $f : [0, \rho] \to (0, \infty)$ . Thus, f[A] has positive diagonal entries for any  $A \in \mathcal{P}_N(\overline{D}(0, \rho))$ , whence (3.2) is never an equality.

It remains to prove (1); here we sketch only the argument for  $A = uu^*$  of rank one. Thus u has pairwise distinct entries by assumption, with N > 1. Suppose for contradiction that det f[A] = 0. Then,

$$\sum_{j=0}^{N-1} \frac{|s_{\mu(M,N,j)}(\sqrt{\rho},\dots,\sqrt{\rho})|^2}{c_j} =: \mathcal{C}(\mathbf{c};z^M;N,\rho) = \sum_{j=0}^{N-1} \frac{|s_{\mu(M,N,j)}(\mathbf{u})|^2}{c_j}$$

using (2.4). Now use the fact that the coefficients of any Schur polynomial are non-negative, to show that

$$|s_{\mu(M,N,j)}(\mathbf{u})| = s_{\mu(M,N,j)}(\sqrt{\rho},\dots,\sqrt{\rho}) = \binom{M}{j}\binom{M-j-1}{N-j-1}\rho^{(M-j)/2} \qquad \forall j$$

Consider the case j = N - 1, which corresponds to the partition  $\mu(M, N, N - 1) = (M - N + 1, 0, ..., 0)$ . By [19, Chapter I, Equation (5.12)], the Schur polynomial  $s_{\mu(M,N,N-1)}$  is a sum of  $\binom{M}{N-1}$  monomials  $\mathbf{u}^{\mathbf{t}}$  corresponding to semi-standard Young tableaux (i.e.,  $\mathbf{t} = (t_1, ..., t_N)$  with  $\sum_{j=0}^{N-1} t_j = M - N + 1$ ). Now using the triangle inequality, all monomials  $\mathbf{u}^{\mathbf{t}}$  are equal; since  $u_1^{M-N}u_j$  is such a monomial for all j, we get  $u_1 = \cdots = u_N$ , a contradiction. Hence det f[A] > 0 as claimed.

Theorem 1.4 also fits naturally into the framework of spectrahedra and the matrix cube problem [6, 20]; see [1] for more details.

#### 3.2 Rayleigh quotients

Given a domain  $K \subset \mathbb{C}$ , functions  $g, h : K \to \mathbb{C}$ , and a set of matrices  $\mathcal{P} \subset \bigcup_{N \ge 1} \mathcal{P}_N(K)$ , define  $\mathcal{C}(h; g; \mathcal{P})$  to be the smallest real number such that  $g[A] \le \mathcal{C}(h; g; \mathcal{P}) \cdot h[A]$  for all  $A \in \mathcal{P}$ . That is,  $\mathcal{C}(h; g; \mathcal{P})$  is the *extreme critical value* of the family of linear pencils  $\{-g[A] + \mathbb{R}h[A] : A \in \mathcal{P}\}$ . This notation helps achieve a uniform and consistent formulation of the aforementioned theorems by Schoenberg and Horn, Theorem 1.4 and its consequences, as well as other results in the literature. See [1, Section 6] for a comprehensive survey of numerous such results.

Given  $\mathbf{c} = (c_0, \dots, c_{N-1}) \in (0, \infty)^N$ , define the polynomial  $h_{\mathbf{c}}(z) := \sum_{j=0}^{N-1} c_j z^j$ . By Theorem 1.4,

$$\mathcal{C}(\mathbf{c}; z^M; N, \rho) = \mathcal{C}(h_{\mathbf{c}}; z^M; \mathcal{P}), \qquad \forall \mathcal{P}^1_N((0, \rho)) \subset \mathcal{P} \subset \mathcal{P}_N(\overline{D}(0, \rho)).$$
(3.4)

We now discuss an alternate, variational approach to proving Theorem 1.4, which proceeds as follows:

- (I) Bound  $A^{\circ M}$  by lower Hadamard powers for a *single* matrix A, i.e., by  $\alpha_A \cdot h_c[A]$  for the smallest constant  $\alpha_A > 0$ .
- (II) Now take the supremum of  $\alpha_A$  over all matrices  $A \in \mathcal{P}_N(\overline{D}(0,\rho))$ .

Notice that the first step (I) simply involves computing the extreme critical value  $\alpha_A = C(h_c; z^M; A)$ , using the above notation. This and an improved understanding of ker  $h_c[A]$ , can be achieved as follows:

**Proposition 3.5** Fix  $\rho > 0$ , integers  $M \ge N \ge 1$ , scalars  $c_0, \ldots, c_{N-1} > 0$ , and  $A \in \mathcal{P}_N(\mathbb{C})$ . Define

$$\mathcal{K}(A) := \ker h_{\mathbf{c}}[A] = \ker (c_0 \mathbf{1}_{N \times N} + c_1 A + \dots + c_{N-1} A^{\circ (N-1)}).$$
(3.6)

Then  $\mathcal{K}(A) = \bigcap_{n>0} \ker A^{\circ n}$ , and the extreme critical value is finite for all A:

$$\mathcal{C}(h_{\mathbf{c}}; z^{M}; A) = \sup_{\mathbf{u} \in \mathcal{K}(A)^{\perp} \setminus \{\mathbf{0}\}} \frac{\mathbf{u}^{*} A^{\circ M} \mathbf{u}}{\mathbf{u}^{*} \left( \sum_{j=0}^{N-1} c_{j} A^{\circ j} \right) \mathbf{u}} \leq \mathcal{C}(\mathbf{c}; z^{M}; N, \rho), \qquad \forall A \in \mathcal{P}_{N}(\overline{D}(0, \rho)) \setminus \{0\}.$$

Moreover, the bound  $C(\mathbf{c}; z^M; N, \rho)$  is sharp, and is obtained as the supremum of the Rayleigh constant  $C(h_{\mathbf{c}}; z^M; A)$  as A runs over the smaller set  $\mathcal{P}^1_N((\rho - \epsilon, \rho))$  for any  $\epsilon \in (0, \rho)$ .

**Sketch of proof.** The first step is to show how the Schur polynomials  $s_{\mu(M,N,j)}$  in Theorem 2.2 serve an additional purpose: they are precisely the "universal coefficients" involved in expressing  $A^{\circ M}$  as a combination of lower Hadamard powers, for any matrix A and over *any* field  $\mathbb{F}$ . More precisely, if A is an  $N \times N$  matrix with entries in  $\mathbb{F}$ , and  $\mathbf{a}_1, \ldots, \mathbf{a}_N$  are its rows, then we first claim that

$$A^{\circ M} = \sum_{j=0}^{N-1} D_{M,j}(A) A^{\circ j},$$
(3.7)

where  $D_{M,j}(A)$  is the diagonal matrix  $(-1)^{N-j-1} \operatorname{diag}(s_{\mu(M,N,j)}(\mathbf{a}_1), \ldots, s_{\mu(M,N,j)}(\mathbf{a}_N))$ . The claim follows by working with distinct transcendental variables  $s_1, \ldots, s_N$  and solving the equation  $V(\mathbf{u})\mathbf{s} = \mathbf{u}^{\circ M}$  for  $\mathbf{s}$ , where  $V(\mathbf{u}) := (u_i^{j-1})$  is the Vandermonde matrix, and  $\mathbf{s} := (s_1, \ldots, s_N)^T$ . The solution, via Cramer's rule, is given by:  $s_i = (-1)^{N-i} s_{\mu(M,N,i-1)}(\mathbf{u})$ ; now specialize to  $\mathbf{u} = \mathbf{a}_j^T$  for all j.

Having proved the claim, the second step is to show that  $\mathcal{K}(A) = \ker h_{\mathbf{c}}[A] \subset \ker A^{\circ M}$  for all  $M \ge 0$ . This is obvious if  $0 \le M < N$ , while for  $M \ge N$ , we use (3.7) to compute:

$$h_{\mathbf{c}}[A]\mathbf{v} = 0 \implies A^{\circ j}\mathbf{v} = 0 \ (0 \le j < N) \implies \sum_{j=0}^{N-1} D_{M,j}(A)A^{\circ j}\mathbf{v} = 0 \implies A^{\circ M}\mathbf{v} = 0.$$

It follows that  $\mathcal{K}(A) \subset \bigcap_{n \geq 0} \ker A^{\circ n}$ . The reverse inclusion is easy to show, as is (the equality in) the next assertion. The subsequent inequality and the last sentence in the result follow from Theorem 1.4.  $\Box$ 

It is also of interest to find a closed-form expression for the generalized Rayleigh quotient  $C(h_c; z^M; A)$  for a given matrix A. The following result provides two such expressions, consequently revealing new and unexpected connections between Rayleigh quotients and Schur polynomials.

**Proposition 3.8** Fix integers  $M \ge N \ge 1$  and positive scalars  $c_0, \ldots, c_{N-1} > 0$ . Then,

$$\mathcal{C}(h_{\mathbf{c}}; z^{M}; A) = \varrho(h_{\mathbf{c}}[A]^{\dagger/2} A^{\circ M} h_{\mathbf{c}}[A]^{\dagger/2}), \qquad \forall A \in \mathcal{P}_{N}(\mathbb{C}) \setminus \{0\},$$
(3.9)

where  $C^{\dagger/2}$ ,  $\varrho(C)$  denote the principal square root of the Moore-Penrose inverse of C, and the spectral radius of C, respectively. For instance, if  $A = \mathbf{uu}^*$  with  $\mathbf{u}$  having distinct coordinates, then

$$\mathcal{C}(h_{\mathbf{c}}; z^{M}; \mathbf{u}\mathbf{u}^{*}) = (\mathbf{u}^{\circ M})^{*} h_{\mathbf{c}}[\mathbf{u}\mathbf{u}^{*}]^{\dagger} \mathbf{u}^{\circ M} = \sum_{j=0}^{N-1} \frac{|s_{\mu(M,N,j)}(\mathbf{u})|^{2}}{c_{j}}.$$
(3.10)

**Sketch of proof.** The proof of (3.9) uses the theory of Kronecker normal forms and Rayleigh quotients, and is omitted for brevity. To show the first equality in (3.10), set  $\mathbf{v} := h_{\mathbf{c}}[\mathbf{u}\mathbf{u}^*]^{\dagger/2}\mathbf{u}^{\circ M}$ . Then standard computations show that  $\mathcal{C}(h_{\mathbf{c}}; z^M; \mathbf{u}\mathbf{u}^*) = \varrho(\mathbf{v}\mathbf{v}^*) = \mathbf{v}^*\mathbf{v} = (\mathbf{u}^{\circ M})^*h_{\mathbf{c}}[\mathbf{u}\mathbf{u}^*]^{\dagger}\mathbf{u}^{\circ M}$ .

Finally, we show that the last equality in (3.10) holds more generally, for any rank-one matrix  $A = \mathbf{u}\mathbf{v}^T$ , where  $\mathbf{u}, \mathbf{v}$  are vectors with distinct coordinates in any field  $\mathbb{F}$ . Indeed, notice by the proof of (2.5) that

$$h_{\mathbf{c}}[\mathbf{u}\mathbf{v}^T] = X(\mathbf{u}, \mathbf{n}_{\min}) \operatorname{diag}(c_0, \dots, c_{N-1}) X(\mathbf{v}, \mathbf{n}_{\min})^T$$
, where  $\mathbf{n}_{\min} := (0, 1, \dots, N-1)$ .

Moreover,  $X(\mathbf{u}, \mathbf{n}_{\min})$  is precisely  $V(\mathbf{u})$ , the Vandermonde matrix  $(u_i^{j-1})$ . Now the proof of Proposition 3.5 shows that  $V(\mathbf{u})^{-1}\mathbf{u}^{\circ M} = ((-1)^{N-j-1}s_{\mu(M,N,j)}(\mathbf{u}))_{j=0}^{N-1} =: \mathbf{s}_N(\mathbf{u})$ , say. Hence,

$$(\mathbf{v}^{\circ M})^T h_{\mathbf{c}} [\mathbf{u}\mathbf{v}^T]^{-1} \mathbf{u}^{\circ M} = (V(\mathbf{v})^{-1}\mathbf{v}^{\circ M})^T \operatorname{diag}(c_0, \dots, c_{N-1})^{-1} (V(\mathbf{u})^{-1}\mathbf{u}^{\circ M})$$
  
=  $\mathbf{s}_N (\mathbf{v})^T \operatorname{diag}(c_0, \dots, c_{N-1})^{-1} \mathbf{s}_N (\mathbf{u}) = \sum_{j=0}^{N-1} \frac{s_{\mu(M,N,j)}(\mathbf{u})s_{\mu(M,N,j)}(\mathbf{v})}{c_j}. \ \Box$ 

Equation (3.10) provides an alternate explanation of how and why Schur polynomials occur in the extreme critical value  $C(\mathbf{c}; z^M; N, \rho)$ , by considering the matrices in  $\mathcal{P}_N^1((0, \rho))$ . Having carried out step (I) in trying to prove Theorem 1.4 by an alternate approach (see the previous page), a natural question is to ask if it is possible to maximize the function  $\Psi_{\mathbf{c},M} : A \mapsto C(h_{\mathbf{c}}, z^M; A)$  to obtain  $C(\mathbf{c}; z^M; N, \rho)$ , as in step (II). Observe by (3.9) that the spectral map  $\Psi_{\mathbf{c},M}$  is continuous on the open dense subset of the cone given by det  $h_{\mathbf{c}}[A] \neq 0$ . However,  $\Psi_{\mathbf{c},M}$  turns out to *not* be continuous on all of  $\mathcal{P}_N(\overline{D}(0,\rho))$ , or even on  $\mathcal{P}_N^1([0,\rho])$ . Specifically, it is not continuous at the matrix  $A = \rho \mathbf{1}_{N \times N}$ . This spectral discontinuity phenomenon warrants further exploration, and is to be the subject of future work [2].

#### Stratification of the cone, and the simultaneous kernels 4

In the final section, we take a closer look at the simultaneous kernel  $\mathcal{K}(A)$  defined in (3.6). As we now discuss, this space crucially depends on a canonical block decomposition of the matrix A. We begin by isolating this refined structure. Consider the following two examples:

$$A_1 := \begin{pmatrix} 5 \cdot \mathbf{1}_{a \times a} & B \\ B^* & 2 \cdot \mathbf{1}_{b \times b} \end{pmatrix} \in \mathcal{P}_{a+b}(\mathbb{C}), \qquad A_2 := \begin{pmatrix} 5 & -5 & u_1 \\ -5 & 5 & u_2 \\ \overline{u_1} & \overline{u_2} & 2 \end{pmatrix} \in \mathcal{P}_3(\mathbb{C}).$$

Given the positivity of  $A_1, A_2$ , one can show that all entries of B are equal, while  $u_1 = -u_2$ . In fact, if entries in each diagonal block of a positive semidefinite matrix lie in a G-orbit for some subgroup  $G \subset \mathbb{C}^{\times}$ , this imposes constraints on the off-diagonal blocks. This is distilled into the following result.

**Theorem 4.1** Fix a subgroup  $G \subset \mathbb{C}^{\times}$ , an integer  $N \geq 1$ , and a non-zero matrix  $A \in \mathcal{P}_N(\mathbb{C})$ . There exists a partition  $\pi^G(A) := \{I_1, \ldots, I_k\}$  of  $\{1, \ldots, N\}$  (unique up to relabelling), satisfying:

- 1. Each diagonal block  $A_{I_i}$  of A is a submatrix with rank at most one.
- 2. The entries of each diagonal block  $A_{I_i}$  lie in a single G-orbit.
- 3. The diagonal blocks  $A_{I_i}$  of A satisfying (1), (2) have maximal size.

In this case, each off-diagonal block of A also has rank at most one, with all its entries in a single G-orbit.

For instance, for two choices of the group G the partition  $\pi^G(A)$  is easily interpreted:

1.  $G = \{1\}$ , in which case all entries in a diagonal (or off-diagonal) block of A are equal.

2.  $G = S^1$ , in which case all entries in a diagonal (or off-diagonal) block of A are equal in modulus.

**Sketch of proof.** Suppose  $\{I_1, \ldots, I_k\}$  is any partition of  $\{1, \ldots, N\}$  satisfying conditions (1), (2). Let  $1 \leq i \neq j \leq k$ , and  $1 \leq l < l' < m \leq N$ , with  $l, l' \in I_i$  and  $m \in I_j$ . Consider the submatrix  $B := A_{\{l,l',m\}} = \begin{pmatrix} a & ag & b \\ a\overline{g} & a|g|^2 & c \\ \overline{b} & \overline{c} & d \end{pmatrix}, \text{ where } a, d \ge 0, \ g, \overline{g} \in G, \ b, c \in \mathbb{C}. \text{ We claim that } c \in b \cdot G, \text{ and that }$ 

Hence either a = 0, in which case b = c = 0, by the positivity of B, or  $c = b\overline{q}$ . The proof repeatedly uses

computations along similar lines, to show that there exists  $C \in \mathcal{P}_k(\mathbb{C})$  with  $\operatorname{rank}(C) = \operatorname{rank}(A)$ , and vectors  $\mathbf{u}_j \in \mathbb{C}^{|I_j|}$  with entries in a single G-orbit, such that  $A_{I_i \times I_j} = c_{ij} \mathbf{u}_i \mathbf{u}_j^*$ , for all  $1 \le i, j \le k$ .  $\Box$ 

Denote by  $(\Pi_N, \prec)$  the poset of all partitions of  $\{1, \ldots, N\}$  under refinement. Then one has the partition map  $\pi^G : \mathcal{P}_N(\mathbb{C}) \to \Pi_N$ , sending 0 to  $\{\{1, \ldots, N\}\}$  and all other matrices A to  $\pi^G(A)$ . Define  $\mathcal{S}_{\pi}^{G}$  to be the fiber of this map:

$$\mathcal{S}_{\pi}^{G} := \{ A \in \mathcal{P}_{N}(\mathbb{C}) : \pi^{G}(A) = \pi \}, \qquad \forall \pi \in \Pi_{N}.$$

$$(4.2)$$

**Corollary 4.3** Fix a subgroup  $G \subset \mathbb{C}^{\times}$ . The sets  $S_{\pi}^{G}$  form a Schubert cell-type stratification of the cone:

$$\mathcal{P}_{N}(\mathbb{C}) = \bigsqcup_{\pi \in \Pi_{N}} \mathcal{S}_{\pi}^{G}, \qquad \overline{\mathcal{S}_{\pi}^{G}} = \bigsqcup_{\pi' \prec \pi} \mathcal{S}_{\pi'}^{G}, \qquad \forall N \ge 1, \ \pi \in \Pi_{N}.$$
(4.4)

Moreover, every  $A \in \mathcal{P}_N(\mathbb{C})$  has rank at most  $|\pi^{\mathbb{C}^{\times}}(A)|$ .

The stratification of the cone  $\mathcal{P}_N(\mathbb{C})$  is noteworthy in that the generalized Rayleigh quotient map  $\Psi_{\mathbf{c},M}$ (defined in Section 3.2) is discontinuous at the point  $\rho \mathbf{1}_{N \times N}$  as one is jumping across strata  $\mathcal{S}_{\pi}^{\{1\}}$ .

Motivated by Proposition 3.5, a precise description of the simultaneous kernel  $\mathcal{K}(A) = \bigcap_{n \ge 0} \ker A^{\circ n}$  is in order. It turns out that the map  $A \mapsto \mathcal{K}(A)$  depends crucially (and solely) on the stratification.

**Theorem 4.5** The simultaneous kernel map  $A \mapsto \mathcal{K}(A)$  is constant on each stratum  $\mathcal{S}^{\{1\}}_{\pi}$ , i.e.,

$$\mathcal{K}: \mathcal{P}_N(\mathbb{C}) \longrightarrow \Pi_N \longrightarrow \bigsqcup_{r=0}^{N-1} \operatorname{Gr}(r, \mathbb{C}^N)$$

sends every matrix  $A \in S_{\pi}^{\{1\}}$  to a fixed subspace

$$\mathcal{K}_{\pi} := \ker \oplus_{j} \mathbf{1}_{I_{j} \times I_{j}} = \oplus_{j} \ker \mathbf{1}_{I_{j} \times I_{j}} \in \operatorname{Gr}(N - |\pi|, \mathbb{C}^{N}),$$

where  $\pi = \{I_j\}$ , and  $\operatorname{Gr}(r, \mathbb{C}^N)$  is the complex Grassmann manifold of r-dimensional subspaces of  $\mathbb{C}^N$ .

The proof of this result is fairly involved, and we refer the reader to [1, Section 5] for details.

We conclude with the following surprising consequence of Theorem 4.5: as A runs over the uncountable set of matrices in  $\mathcal{P}_N(\mathbb{C})$ , the set of simultaneous kernels  $\mathcal{K}(A) = \bigcap_{n\geq 0} \ker A^{\circ n}$  is, nevertheless, a finite set of subspaces of  $\mathbb{C}^N$ , indexed by  $\Pi_N$ . This is in stark contrast to the situation for the usual matrix powers, in which case  $\bigcap_{n\geq 1} \ker A^n = \ker A$  can vary over an uncountable set of subspaces of  $\mathbb{C}^N$ .

Other ramifications of this work, as well as complete proofs can be found elsewhere [1, 2].

#### References

- A. Belton, D. Guillot, A. Khare, and M. Putinar. Matrix positivity preservers in fixed dimension. I. *Adv. Math.*, 298:325–368, 2016.
- [2] A. Belton, D. Guillot, A. Khare, and M. Putinar. Matrix positivity preservers in fixed dimension. II. Work in progress.
- [3] C. Berg, J.P.R. Christensen, and P. Ressel. Harmonic analysis on semigroups: Theory of positive definite and related functions, volume 100 of Graduate Texts in Mathematics. Springer, Berlin, 1984.
- [4] C. Berg and E. Porcu. From Schoenberg coefficients to Schoenberg functions. *Constr. Approx.*, published online, DOI: 10.1007/s00365-016-9323-9, 2016.
- [5] P.J. Bickel and E. Levina. Covariance regularization by thresholding. Ann. Statist., 36(6):2577–2604, 2008.
- [6] G. Blekherman, P.A. Parrilo, and R.R. Thomas, editors. *Semidefinite optimization and convex algebraic geometry*, volume 13 of *MOS-SIAM Series on Optimization*. SIAM, Philadelphia, 2013.
- [7] S. Bochner. Hilbert distances and positive definite functions. Ann. of Math. (2), 42:647–656, 1941.
- [8] J.P.R. Christensen and P. Ressel. Functions operating on positive definite matrices and a theorem of Schoenberg. *Trans. Amer. Math. Soc.*, 243:89–95, 1978.

- [9] C.H. FitzGerald and R.A. Horn. On fractional Hadamard powers of positive definite matrices. J. *Math. Anal. Appl.*, 61(3):633–642, 1977.
- [10] D. Guillot, A. Khare, and B. Rajaratnam. Complete characterization of Hadamard powers preserving Loewner positivity, monotonicity, and convexity. J. Math. Anal. Appl., 425(1):489–507, 2015.
- [11] D. Guillot, A. Khare, and B. Rajaratnam. Preserving positivity for rank-constrained matrices. *Trans. Amer. Math. Soc.*, in press (arXiv: 1406.0042), 2016.
- [12] D. Guillot, A. Khare, and B. Rajaratnam. Preserving positivity for matrices with sparsity constraints. *Trans. Amer. Math. Soc.*, published online, DOI: 10.1090/tran6669, 2016.
- [13] D. Guillot and B. Rajaratnam. Functions preserving positive definiteness for sparse matrices. *Trans. Amer. Math. Soc.*, 367(1):627–649, 2015.
- [14] J.W. Helton, S. McCullough, M. Putinar, and V. Vinnikov. Convex matrix inequalities versus linear matrix inequalities. *IEEE Trans. Automat. Control*, 54(5):952–964, 2009.
- [15] A. Hero and B. Rajaratnam. Large-scale correlation screening. J. Amer. Statist. Assoc., 106:1540– 1552, 2011.
- [16] F. Hiai. Monotonicity for entrywise functions of matrices. Lin. Alg. Appl., 431(8):1125–1146, 2009.
- [17] R.A. Horn. The theory of infinitely divisible matrices and kernels. *Trans. Amer. Math. Soc.*, 136:269–286, 1969.
- [18] K. Löwner. Über monotone Matrixfunktionen. Math. Z., 38(1):177–216, 1934.
- [19] I.G. Macdonald. Symmetric functions and Hall polynomials. Oxford Mathematical Monographs. The Clarendon Press, Oxford University Press, New York, second edition, 1995. With contributions by A. Zelevinsky, Oxford Science Publications.
- [20] A. Nemirovski. Advances in convex optimization: conic programming. In *International Congress of Mathematicians. Vol. I*, pages 413–444. Eur. Math. Soc., Zürich, 2007.
- [21] A.J. Rothman, E. Levina, and J. Zhu. Generalized thresholding of large covariance matrices. *J. Amer. Statist. Assoc.*, 104(485):177–186, 2009.
- [22] W. Rudin. Positive definite sequences and absolutely monotonic functions. *Duke Math. J*, 26(4):617–622, 1959.
- [23] I.J. Schoenberg. Positive definite functions on spheres. Duke Math. J., 9(1):96–108, 1942.
- [24] J. Schur. Bemerkungen zur Theorie der beschränkten Bilinearformen mit unendlich vielen Veränderlichen. J. reine angew. Math., 140:1–28, 1911.
- [25] R.P. Stanley. Theory and applications of plane partitions. Part 2. Stud. Appl. Math., 50(3):259–279, 1971.
- [26] J. von Neumann and I.J. Schoenberg. Fourier integrals and metric geometry. *Trans. Amer. Math. Soc.*, 50:226–251, 1941.